



Chaotic Magnetic Pendulum

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Problem

Consider a pendulum consisting of a magnetic bob attached to a string. If the pendulum is allowed to swing over a structure of permanent magnets, it will display complex motion.

Study the pendulum dynamics and its dependence on the number of permanent magnets and their arrangements

— International Physicist Tournament 2021



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Simulation Set Up

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- 

1. Assumptions in 2D Simulation

Small Angle

- Linear Restore
- Static Z

Monopole Magnets

- Like Charges

2. Set up magnets and forces

Force Model

- Componentwise
- Arrays

Static Base Forces

- Drag
- Gravity

```
def ay(x,y,vy):  
    #Contribution from gravity  
    ygrav = -K*y  
  
    #Contribution from drag  
    ydrag = -B*vy  
  
    #Contribution from magnet one  
    if y-MY[0] == 0:  
        ymag1=0  
    else:  
        ymag1 = sign(MY[0]-y)*(J*S[0]*(abs(np.cos(np.arctan((x-MX[0])/(y-MY[0]))))))/((x-MX[0])**2+(y-MY[0])**2+(Z)**2)**1.5  
    #Contribution from magnet two  
    if y-MY[1] == 0:  
        ymag2=0  
    else:  
        ymag2 = sign(MY[1]-y)*(J*S[1]*(abs(np.cos(np.arctan((x-MX[1])/(y-MY[1]))))))/((x-MX[1])**2+(y-MY[1])**2+(Z)**2)**1.5  
    #Contribution from magnet three  
    if y-MY[2] == 0:  
        ymag3=0  
    else:  
        ymag3 = sign(MY[2]-y)*(J*S[2]*(abs(np.cos(np.arctan((x-MX[2])/(y-MY[2]))))))/((x-MX[2])**2+(y-MY[2])**2+(Z)**2)**1.5  
  
    return ygrav + ydrag + ymag1 + ymag2 + ymag3
```

3. Path Generation - Initial Conditions

- Set up empty arrays
 - N = Number of steps
- Insert initial conditions
 - Index 0

```
#Initial conditions (start with no velocity)
t[0] = 0 #Initial time (in sec)
x[0] = 5 #Initial x position (in m)
y[0] = 1 #Initial y position (in m)
vx[0] = 0 #Initial x velocity (in m/s)
vy[0] = 0 #Initial y velocity (in m/s)
```

```
#Declare main arrays
t = np.empty(N) #Time array
x = np.empty(N) #x position array
y = np.empty(N) #y position array
vx = np.empty(N) #x velocity array
vy = np.empty(N) #y velocity array
```


3. Path Generation - Loop

- Loop through N steps
 - i = index for each array
 - Update x , y values for every i
 - Use the equations of kinematics

```
for i in range(N-1):
    t[i+1] = t[i] + DT

    x[i+1] = x[i]+vx[i]*DT+(aX(x[i],y[i],vx[i]))*(DT**2)*0.5)
    y[i+1] = x[i]+vy[i]*DT+(aY(x[i],y[i],vy[i]))*(DT**2)*0.5)

    vx[i+1] = vx[i] + aX(x[i],y[i],vx[i])*DT
    vy[i+1] = vy[i] + aY(x[i],y[i],vy[i])*DT

#Plot the trajectory
plt.plot(x,y,zorder=1,color='red')
plt.scatter(MX,MY,color='black',zorder=2,label='Fixed magnets')
plt.scatter(x[0],y[0],color='magenta',zorder=3)
title = 'Trajectory for initial position ('+str(x[0])+','+str(y[0])+')'
plt.title(title)
plt.xlabel('x (m)')
plt.ylabel('y (m)')
plt.legend()
plt.show()
```



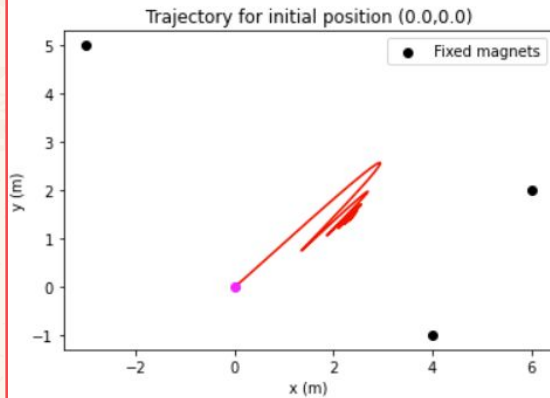

Varying Conditions

1. Initial Position
2. Positions of magnets
3. Strengths of magnets

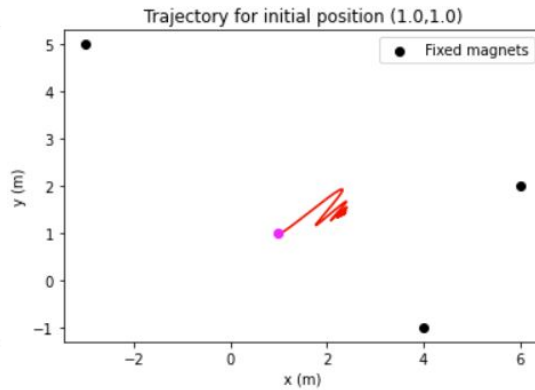
02

Initial Position

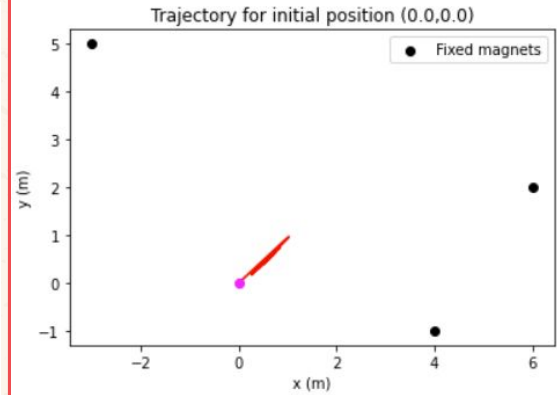
$(0, 0, .25)$



$(1, 1, .25)$

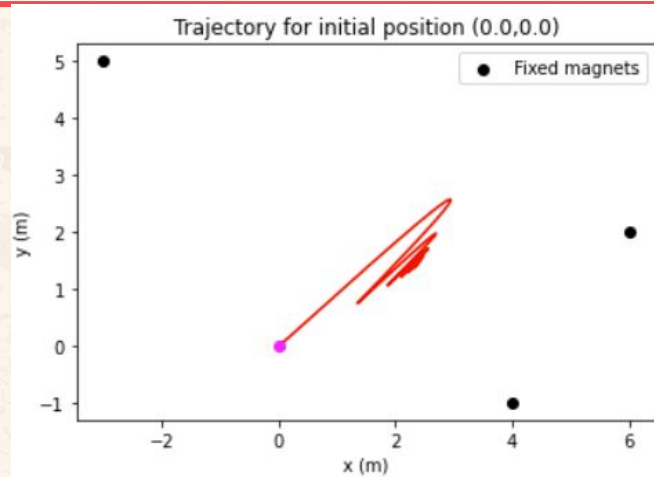


$(0, 0, 5)$

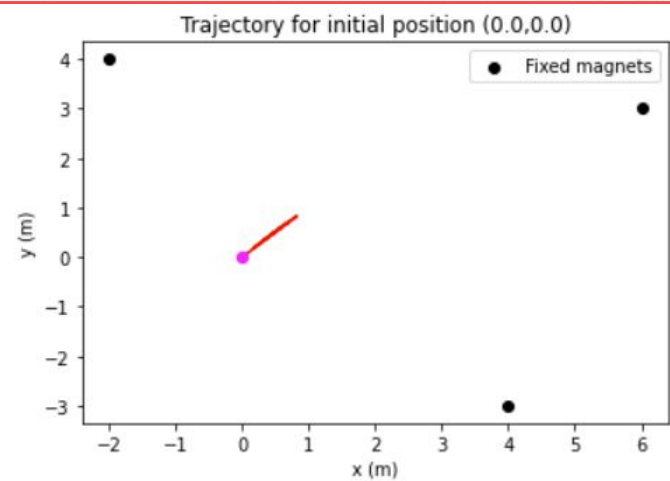


Positions of magnets

$(-3, 5/4, -1/6, 2)$

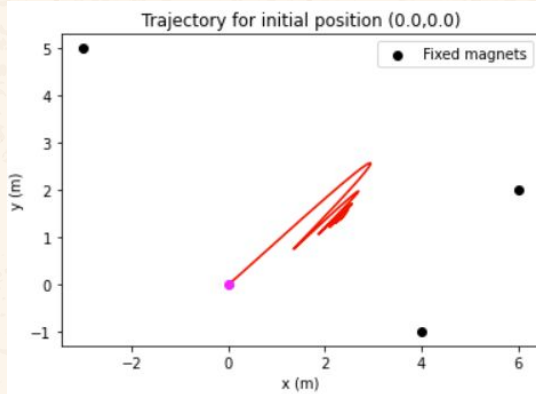


$(4, -3/6, 3/-2, 4)$

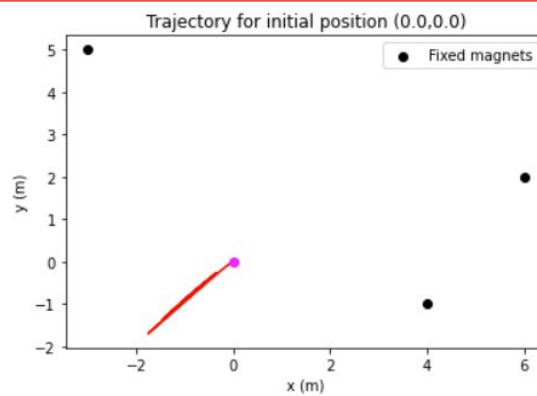


Strengths of magnets

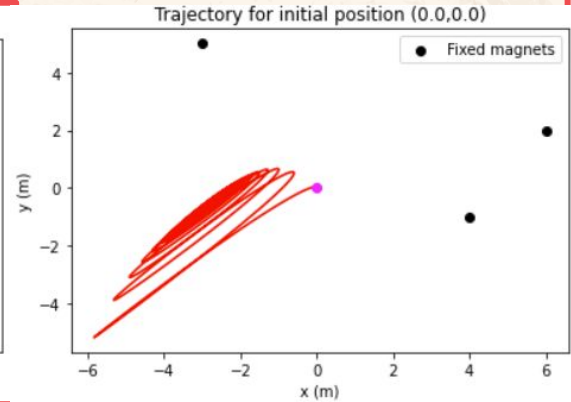
(10, 10, 10)



(-10, -10, -10)



(100, -40, -40)



Animation

- Loop through i to get a set of frames

```
# Initilize writer
metadata = dict(title='2D animation', artist='Matplotlib')
writer = FFMpegWriter(fps=50, metadata=metadata, bitrate=200000)
fig = plt.figure(dpi=200)

fig, ax = plt.subplots()

## SAVE AS MP4 ##
with writer.saving(fig, "magnet.mp4", dpi=200):
    for i in range(N-1):
        ax.clear()

        ax.plot(x,y,zorder=1,color='magenta') Line of path
        ax.scatter(MX,MY,color='black',zorder=2,label='Fixed magnets') Permanent magnets
        ax.scatter(x[i],y[i],color='magenta',zorder=5) Pendulum bob

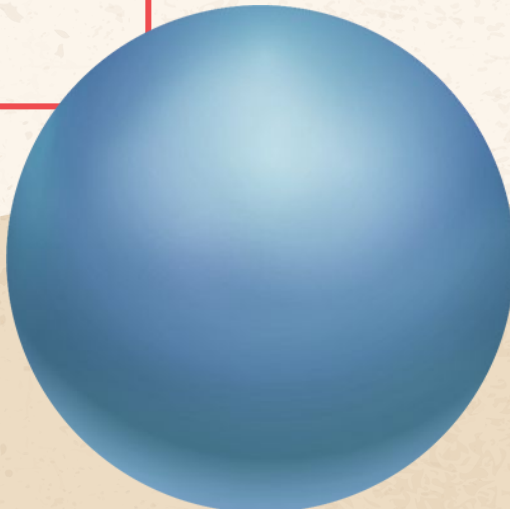
        plt.draw()
        plt.pause(0.00001)
        writer.grab_frame()
```



03

Animation

An interactive illustration of how
the pendulum swings



Animation

- Loop through i to get a set of frames

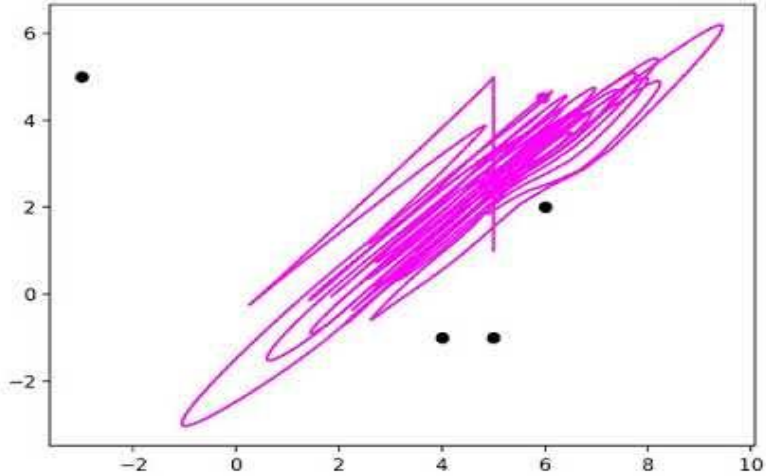
```
# Initilize writer
metadata = dict(title='2D animation', artist='Matplotlib')
writer = FFMpegWriter(fps=50, metadata=metadata, bitrate=200000)
fig = plt.figure(dpi=200)

fig, ax = plt.subplots()

## SAVE AS MP4 ##
with writer.saving(fig, "magnet.mp4", dpi=200):
    for i in range(N-1):
        ax.clear()

        ax.plot(x,y,zorder=1,color='magenta') Line of path
        ax.scatter(MX,MY,color='black',zorder=2,label='Fixed magnets') Permanent magnets
        ax.scatter(x[i],y[i],color='magenta',zorder=5) Pendulum bob

        plt.draw()
        plt.pause(0.00001)
        writer.grab_frame()
```



Demonstration

Path above 4 magnets

Pendulum: $(5, 1, 0)$

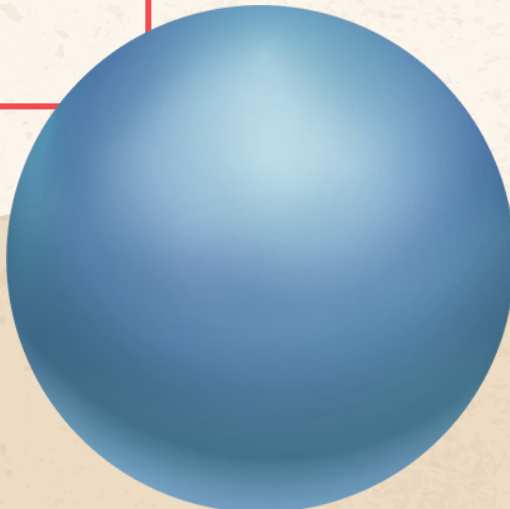
Magnets: $(-3, 5, 0)$ $(4, -1, 0)$ $(6, 2, 0)$ $(5, -1, 0)$



03

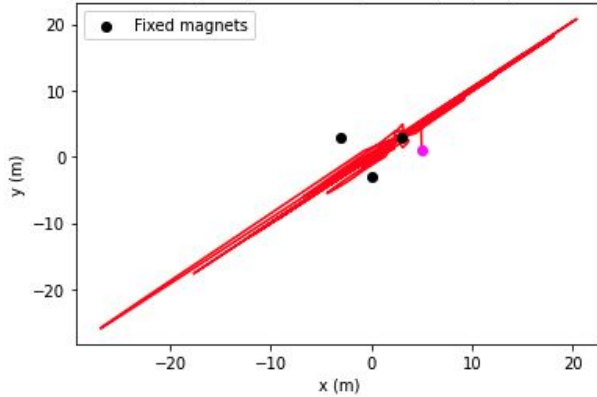
Basins of attraction

Regular patterns in chaotic
behaviour

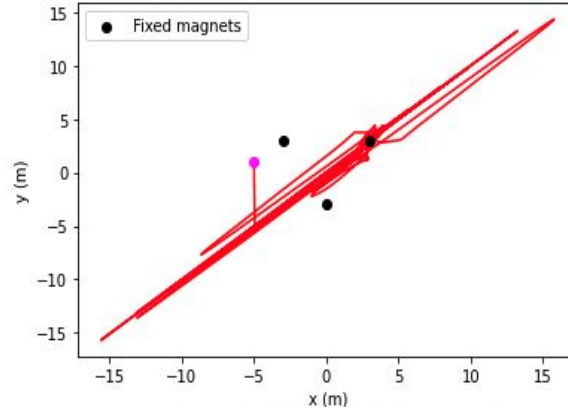


Patterns observed with special magnet positions

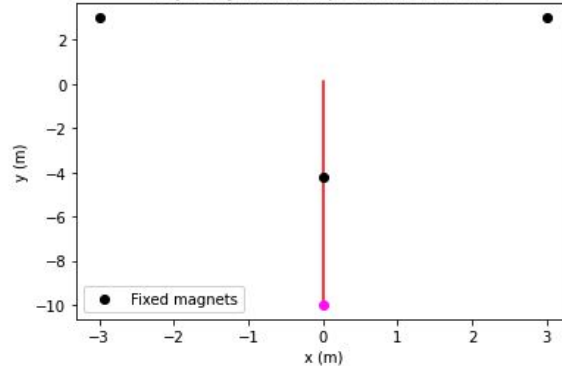
Trajectory for initial position (5.0,1.0)



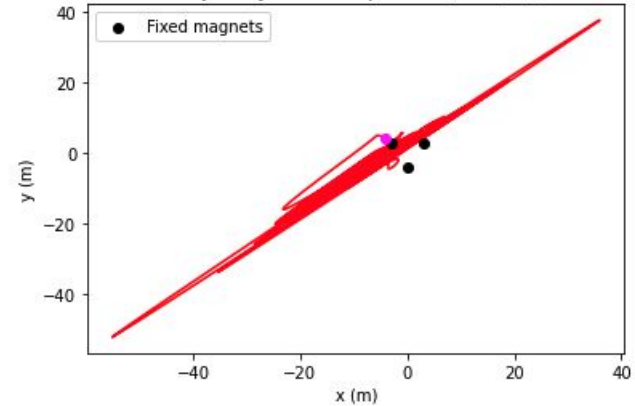
Trajectory for initial position (-5.0,1.0)



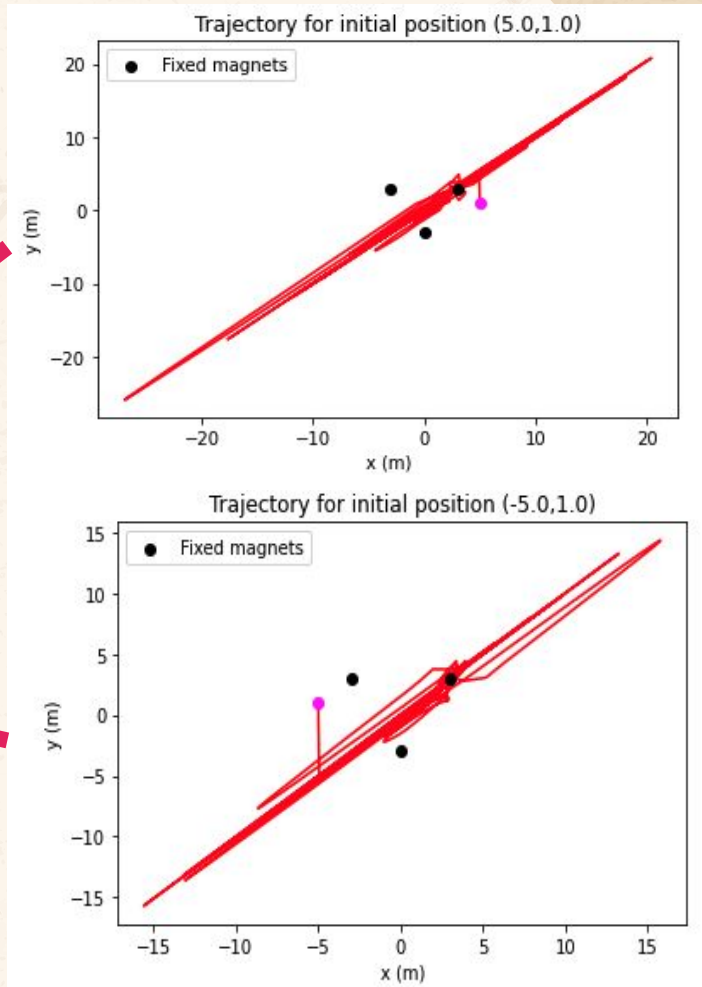
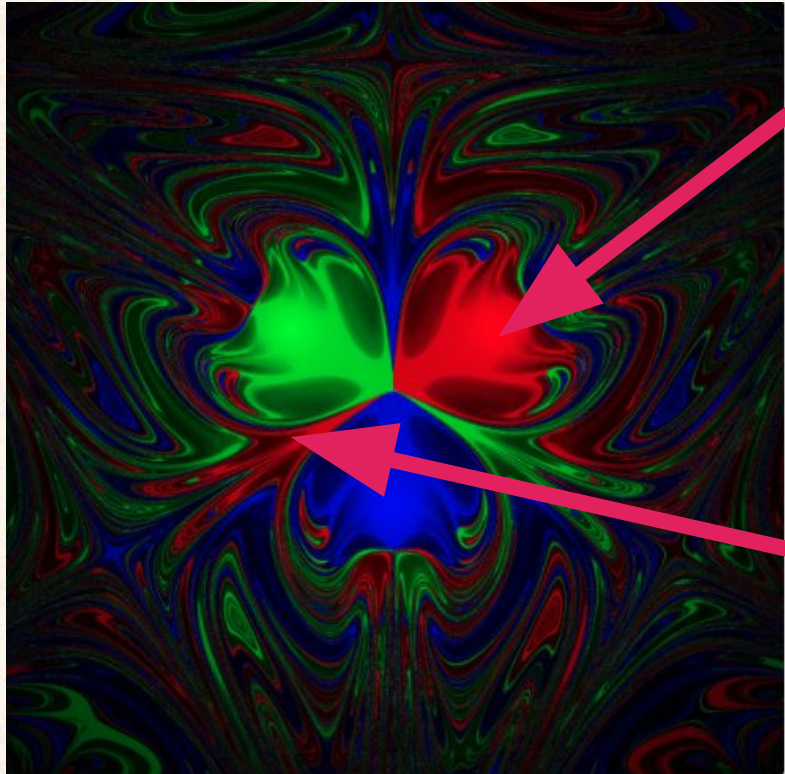
Trajectory for initial position (0.0,-10.0)



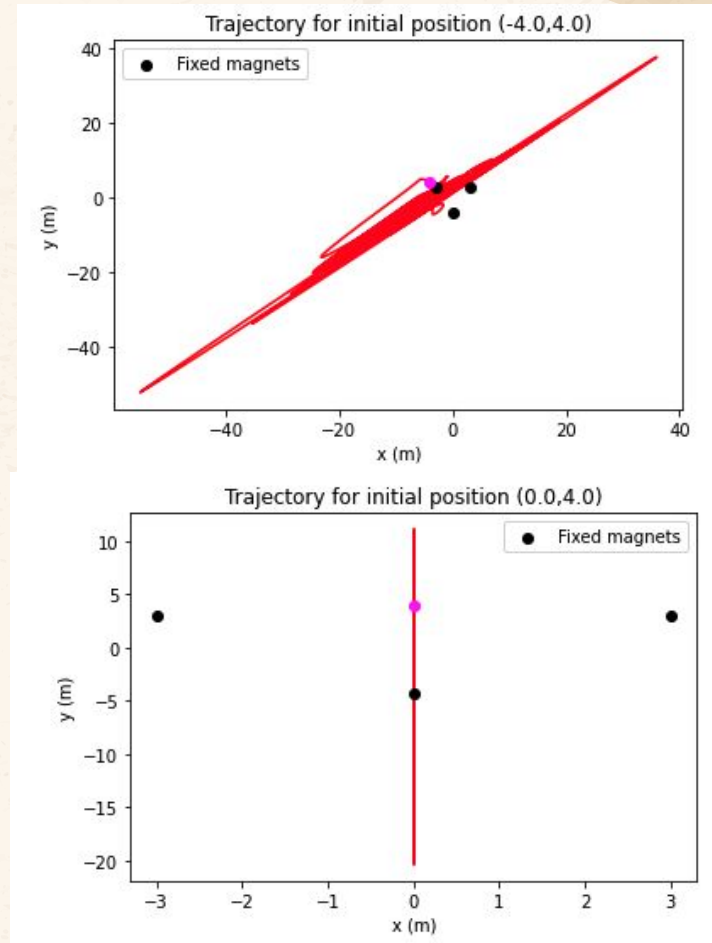
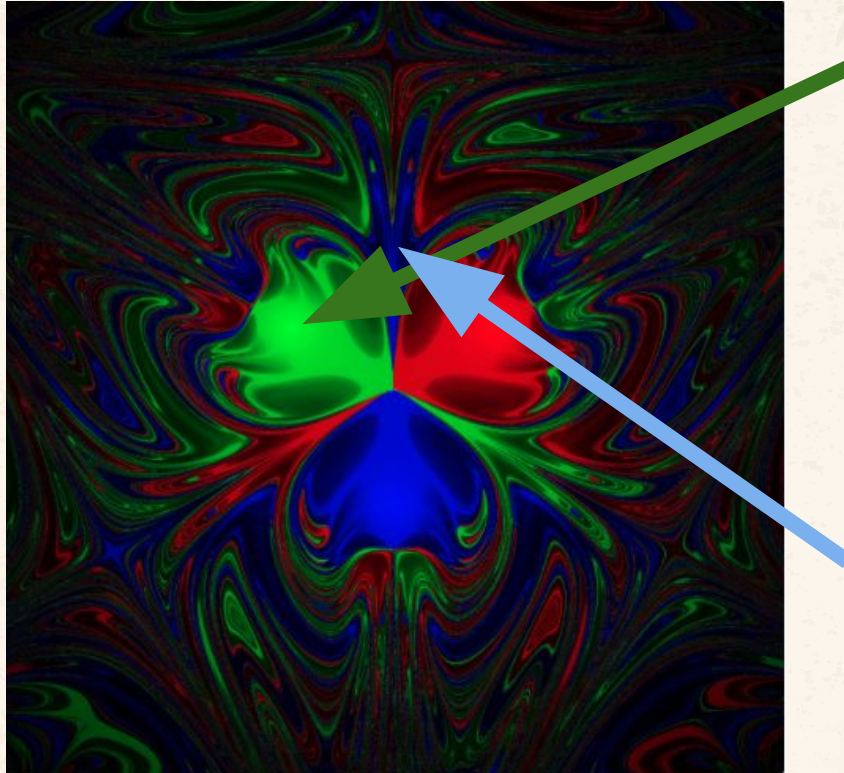
Trajectory for initial position (-4.0,4.0)



Basins of attraction



Basins of attraction





THANK YOU!

References:

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<https://softologyblog.wordpress.com/2012/04/11/chaotic-oscillating-magnetic-pendulum-simulation/>

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